Sheet 1 of 1

	RES						Sheet 1 of 1	
Form \$164 49 U.S. Department Patent and Trade			ent of Commerce ademark Office	Atty. Docket No. 2003P01633 US01		Serial No. 10/770,044		
INFORMATION CITED BY APPLICANT (Use several sheets if necessary)				Applicant Dorin Comaniciu				
				Filling Date 02.02.04		Group 2613		
			U.S. Paten	t Documents				
Examiner							Filling Date	
nitial	Document Number	Date	Name		Class	Subclass	if appropriate	
-/AW/ ·	6445809	9/3/2002	Sasaki et al		382	104		
or. Ref	. missing	country	Foreign Patent	Documents				
	Document Number	Date	Country		Class	Subclass	Translation	
		11/12/2003						
				, Title, Date, Pertinent Pa	iges, etc.)			
/AW/ /AW/	ENKELMANN W: "OBSTACLE DETECTION BY EVALUATION OF OPTICAL FLOW FIELDS FROM IMAGE SEQUENCES" IMAGE AND VISION COMPUTING, GUILDFORD, GB, vol. 9, no. 3, June 1991 (1991—06), pages 160—168, XP009033182 ISSN: 0262—8856 the whole document KRUGER W ET AL: "Real—time estimation and tracking of optical flow vectors for obstacle detection" INTELLIGENT VEHICLES '95 SYMPOSIUM. PROCEEDINGS OF THE DETROIT, MI, USA 25—26 SEPT. 1995, NEW YORK, NY, USA,IEEE, US, 25 September 1995 (1995—09—25), pages 304—309, XP010194134 ISBN: 0—7803—2983—X the whole document							
/AW/	ATTOLICO G ET AL: "Shape recovery of collision zones for obstacle avoidance" INTELLIGENT ROBOTS AND SYSTEMS '91. 'INTELLIGENCE FOR MECHANICAL SYSTEMS, PROCEEDINGS IROS '91. IEEE/RSJ INTERNATIONAL WORKSHOP ON OSAKA, JAPAN 3—5 NOV. 1991, NEW YORK, NY, USA,IEEE, US, 3 November 1991 (1991—11—03), pages 837—841, XP010047248 ISBN: 0—7803—0067—X the whole document							
/AW/	HU Z ET AL: "Tracking cycle: a new concept for simultaneous tracking of multiple moving objects in a typical traffic scene INTELLIGENT VEHICLES SYMPOSIUM, 2000. IV 2000. PROCEEDINGS OF THE IEEE DEARBORN, MI, USA 3—5 OCT. 2000, PISCATAWAY, NJ, USA,IEEE, US, 3 October 2000 (2000—10—03), pages 233—239, XP010528942 ISBN: 0—7803—6363—9 the whole document							
/AW/	Vehicle Guid INTELLIGEN US, vol. VOI	THOMANEK F ET AL: "Obstacle Detection, Tracking And State Estimation For Autonomous Road Vehicle Guidance PROCEEDINGS OF THE IEEE/RSJ INTERNATIONAL CONFERENCE ON INTELLIGENT ROBOTS AND SYSTEMS. RALEIGH, NC., JULY 7 _ 10, 1992, NEW YORK, IEEE, US, vol. VOL. 1 _ 7 July 1992 (1992—07—07), pages 1399—1406, XP010223197 ISBN: 0—7803—0738—0 page 1401, column 2 _ page 1403, column 1						
/AW/	"INDUSTRIA SYMPOSIUM 1997, NEW	SANTOS—VICTOR J ET AL: "On the design of visual behaviors for autonomous systems "INDUSTRIAL ELECTRONICS, 1997. ISIE '97., PROCEEDINGS OF THE IEEE INTERNATIONAL SYMPOSIUM ON GUIMARAES, PORTUGAL 7—11 JULY 1997, NEW YORK, NY, USA,IEEE, US, 7 July 1997 (1997—07—07), pages SS53—SS59, XP010265139 ISBN: 0—7803—3936—3 page SS53, column 1 page SS55, column 2						
Examiner	/Allen Wong/			Date Considered 03/17/2008				